



MAX PLANCK INSTITUTE
FOR DYNAMICS OF COMPLEX
TECHNICAL SYSTEMS
MAGDEBURG



DATA-DRIVEN MODELING OF
COMPLEX PHYSICAL SYSTEMS

Dimensionality Reduction and Metastability Analysis using the Koopman Operator

Feliks Nüske

September 7, 2023

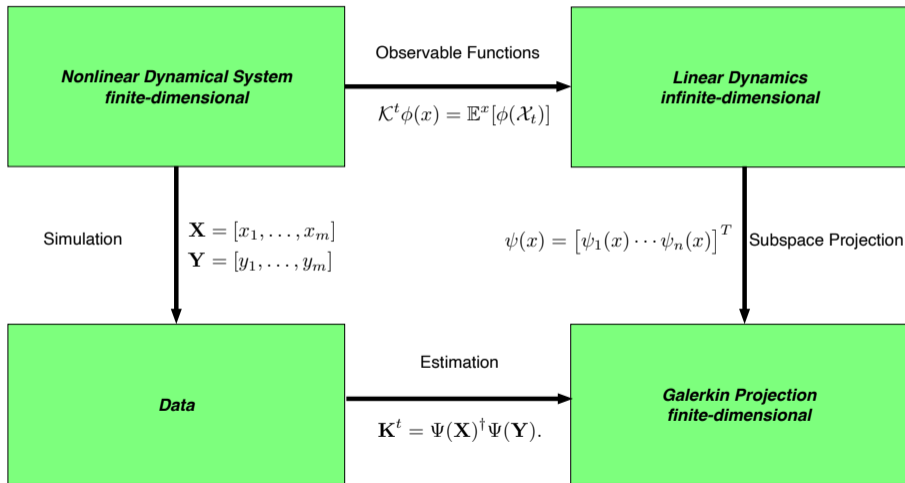


1. The Koopman Operator and EDMD
2. Variational Approach (VAC)
3. EDMD and Kernels
4. Random Fourier Features for EDMD



The Koopman Approach

Main Idea: **lifting** into an **infinite-dimensional** space where the dynamics become **linear**.





Idea: Track the dynamics of a set of **observables** by a **linear map**



Idea: Track the dynamics of a set of **observables** by a **linear map**

- Choose finitely many observables:

$$\psi(x) = [\psi_1(x) \cdots \psi_n(x)]^T .$$



Idea: Track the dynamics of a set of **observables** by a **linear map**

- Choose finitely many observables:

$$\psi(x) = [\psi_1(x) \cdots \psi_n(x)]^T.$$

- Generate transformed snapshot matrices (x_k, y_k **separated** by time t):

$$\Psi(\mathbf{X}) = [\psi(x_1) \mid \cdots \mid \psi(x_m)] \in \mathbb{R}^{n \times m},$$

$$\Psi(\mathbf{Y}) = [\psi(y_1) \mid \cdots \mid \psi(y_m)] \in \mathbb{R}^{n \times m}.$$



Idea: Track the dynamics of a set of **observables** by a **linear map**

- Choose finitely many observables:

$$\psi(x) = [\psi_1(x) \cdots \psi_n(x)]^T.$$

- Generate transformed snapshot matrices (x_k, y_k **separated** by time t):

$$\Psi(\mathbf{X}) = [\psi(x_1) \mid \cdots \mid \psi(x_m)] \in \mathbb{R}^{n \times m},$$

$$\Psi(\mathbf{Y}) = [\psi(y_1) \mid \cdots \mid \psi(y_m)] \in \mathbb{R}^{n \times m}.$$

- Solve **regression** problem (EDMD):

$$\begin{aligned} \mathbf{K}^t &= \operatorname{argmin}_{K \in \mathbb{R}^{n \times n}} \|\Psi(\mathbf{Y}) - \mathbf{K}^T \Psi(\mathbf{X})\|_F \\ &= (\Psi(\mathbf{X})^T \Psi(\mathbf{X}))^{-1} (\Psi(\mathbf{X})^T \Psi(\mathbf{Y})). \end{aligned}$$

Williams et al, *J. Nonlinear Sci.* (2015)



- Assume x_k are **drawn from distribution** ρ :

$$\frac{1}{m} [\Psi(\mathbf{X})^T \Psi(\mathbf{X})]_{ij} = \frac{1}{m} \sum_{k=1}^m \psi_i(x_k) \psi_j(x_k)$$
$$\xrightarrow{m \rightarrow \infty} \mathbb{E}^{\mathcal{X}_0 \sim \rho} [\psi_i(\mathcal{X}_0) \psi_j(\mathcal{X}_0)],$$



- Assume x_k are **drawn from distribution** ρ :

$$\begin{aligned} \frac{1}{m} [\Psi(\mathbf{X})^T \Psi(\mathbf{X})]_{ij} &= \frac{1}{m} \sum_{k=1}^m \psi_i(x_k) \psi_j(x_k) \\ &\xrightarrow{m \rightarrow \infty} \mathbb{E}^{\mathcal{X}_0 \sim \rho} [\psi_i(\mathcal{X}_0) \psi_j(\mathcal{X}_0)], \end{aligned}$$

- and similarly

$$\begin{aligned} \frac{1}{m} [\Psi(\mathbf{X})^T \Psi(\mathbf{Y})]_{ij} &= \frac{1}{m} \sum_{k=1}^m \psi_i(x_k) \psi_j(y_k) \\ &\xrightarrow{m \rightarrow \infty} \mathbb{E}^{\mathcal{X}_0 \sim \rho} [\psi_i(\mathcal{X}_0) \psi_j(\mathcal{X}_t)]. \end{aligned}$$

Williams et al, *J. Nonlinear Sci.* (2015),



- Empirical **Gramian** in Hilbert space L_ρ^2 :

$$\mathbb{E}^{\mathcal{X}_0 \sim \rho}[\psi_i(\mathcal{X}_0)\psi_j(\mathcal{X}_0)] = \int_{\mathbb{X}} \psi_i(x) \psi_j(x) \mathrm{d}\rho(x) = \langle \psi_i, \psi_j \rangle_\rho,$$

- Empirical **Stiffness Matrix** in Hilbert space L_ρ^2 :

$$\mathbb{E}^{\mathcal{X}_0 \sim \rho}[\psi_i(\mathcal{X}_0)\psi_j(\mathcal{X}_t)] = \mathbb{E}^{x \sim \rho}[\psi_i(x) \mathbb{E}[\psi_j(\mathcal{X}_t) | \mathcal{X}_0 = x]].$$



- Empirical **Gramian** in Hilbert space L_ρ^2 :

$$\mathbb{E}^{\mathcal{X}_0 \sim \rho}[\psi_i(\mathcal{X}_0)\psi_j(\mathcal{X}_0)] = \int_{\mathbb{X}} \psi_i(x) \psi_j(x) d\rho(x) = \langle \psi_i, \psi_j \rangle_\rho,$$

- Empirical **Stiffness Matrix** in Hilbert space L_ρ^2 :

$$\mathbb{E}^{\mathcal{X}_0 \sim \rho}[\psi_i(\mathcal{X}_0)\psi_j(\mathcal{X}_t)] = \mathbb{E}^{x \sim \rho}[\psi_i(x) \mathbb{E}[\psi_j(\mathcal{X}_t) | \mathcal{X}_0 = x]].$$

- Using the **Koopman operator**, EDMD becomes a Galerkin method:

$$\begin{aligned} \mathcal{K}^t \phi(x) &= \mathbb{E}[\phi(\mathcal{X}_t) | \mathcal{X}_0 = x] \\ \Rightarrow \mathbb{E}^{\mathcal{X}_0 \sim \rho}[\psi_i(\mathcal{X}_0)\psi_j(\mathcal{X}_t)] &= \int_{\mathbb{X}} \psi_i(x) \mathcal{K}^t \psi_j(x) d\rho(x) = \langle \psi_i, \mathcal{K}^t \psi_j \rangle_\rho. \end{aligned}$$

Williams et al, *J. Nonlinear Sci.* (2015)



The Koopman Semigroup

- Koopman operators form a **semigroup**:

$$\mathcal{K}^{s+t} = \mathcal{K}^s \mathcal{K}^t$$

- Semigroup property gives rise to **infinitesimal generator**:

$$\mathcal{L}f = \lim_{t \rightarrow 0} \frac{1}{t} (\mathcal{K}^t - \text{Id})f.$$

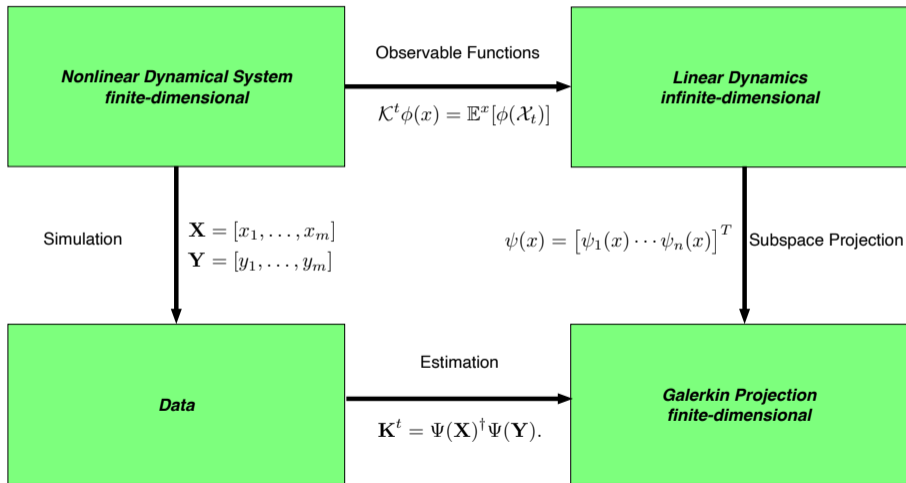
- On the space of observables, the dynamics are linear:

$$\frac{d}{dt} \mathcal{K}^t \phi = \mathcal{L} \mathcal{K}^t \phi.$$



The Koopman Approach

Main Idea: **lifting** into an **infinite-dimensional** space where the dynamics become **linear**.





Summary

- Koopman framework uses a **lifting** into an **infinite-dimensional** space where the dynamics become **linear**.
- EDMD approximates a **Galerkin projection** of \mathcal{K}^t in the **statistical limit**.
- EDMD matrix can be used to **forecast** expectations of ob system observables, potentially over **long timescales**.
- Applications in control, model reduction, metastability analysis, ...

Klus, **FN**, et al, *J. Nonlinear Sci.*, 2018,

Mauroy, Suzuki, Mezic (eds), *Koopman operator in systems and control*, Springer 2020,

Klus, **FN**, Peitz et al, *Physica D*, 2020,

Berry, Giannakis, Harlim, *Notices of the AMS*, 2020.



1. The Koopman Operator and EDMD

2. Variational Approach (VAC)

3. EDMD and Kernels

4. Random Fourier Features for EDMD



Variational Principle

- For **reversible** systems, Koopman operator \mathcal{K}^t is **self-adjoint**.



Variational Principle

- For **reversible** systems, Koopman operator \mathcal{K}^t is **self-adjoint**.
- **Rayleigh variational principle** (RVP) for dominant eigenvalues $1 = \lambda_0(t) \geq \dots \geq \lambda_M(t)$:

$$\sum_{i=0}^M \langle \psi_i, \mathcal{K}^t \psi_i \rangle_{\mu} =: \mathcal{R}(\psi) \leq \sum_{i=0}^M \lambda_i(t) \quad (1)$$

$$\langle \psi_k, \psi_l \rangle_{\mu} = \delta_{kl}. \quad (2)$$



Variational Principle

- For **reversible** systems, Koopman operator \mathcal{K}^t is **self-adjoint**.
- **Rayleigh variational principle** (RVP) for dominant eigenvalues $1 = \lambda_0(t) \geq \dots \geq \lambda_M(t)$:

$$\sum_{i=0}^M \langle \psi_i, \mathcal{K}^t \psi_i \rangle_{\mu} =: \mathcal{R}(\psi) \leq \sum_{i=0}^M \lambda_i(t) \quad (1)$$

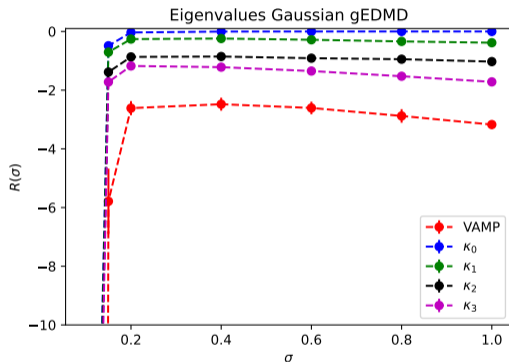
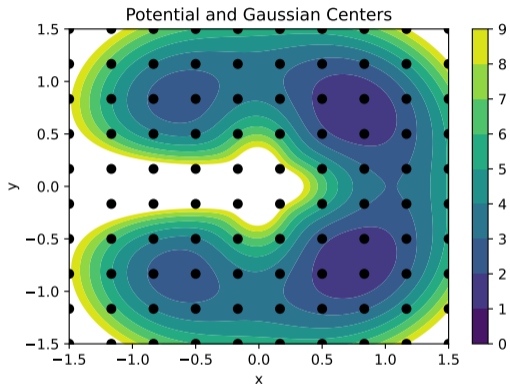
$$\langle \psi_k, \psi_l \rangle_{\mu} = \delta_{kl}. \quad (2)$$

- $\mathcal{R}(\psi)$ can be used as an **objective function**, subject to the constraint (2).
- All quantities in (1-2) can be **estimated from simulation data**:

$$\langle \psi_i, \psi_i \rangle_{\mu} \approx \frac{1}{m} \sum_{k=1}^m \psi_i(x_k) \psi_i(x_k), \quad \langle \psi_i, \mathcal{K}^t \psi_i \rangle_{\mu} \approx \frac{1}{m} \sum_{k=1}^m \psi_i(x_k) \psi_i(y_k).$$



Cross-Validation



Linear VAC: Noé and FN, *SIAM MMS*, 2013, FN, Keller, et al, *JCTC*, 2014,
TICA: Pérez-Hernández et al, *J. Chem. Phys.*, 2013, **Deep Learning:** Mardt et al, *Nat. Commun.*, 2018
Non-reversible systems: Wu and Noé, *J. Nonlinear Sci.*, 2020



- Learning from **short trajectories** and **renewal equations**,
Noé, Schütte, et al, *PNAS* (2009)
Cao, Huang, et al, *J. Chem. Phys.* 2020
- Models for the generator, **system identification**,
Boninsegna, **FN**, Clementi, *J. Chem. Phys.* (2018)
Klus, **FN**, Peitz, et al, *Physica D* (2020)
- Use Koopman models to **enhance exploration**,
Hruska and Clementi, *J. Chem. Phys* (2018)
Sidky, Chen, Ferguson, *Modern Physics*, 2020
Shmilovich and Ferguson, *J Phys. Chem. A* (2023)
- **Error theory** based on concentration inequalities,
Zhang and Zuazua, *Comptes Rendus Math.* (2022)
FN et al, *J. Nonlinear Sci.* (2023)



1. The Koopman Operator and EDMD
2. Variational Approach (VAC)
3. EDMD and Kernels
4. Random Fourier Features for EDMD

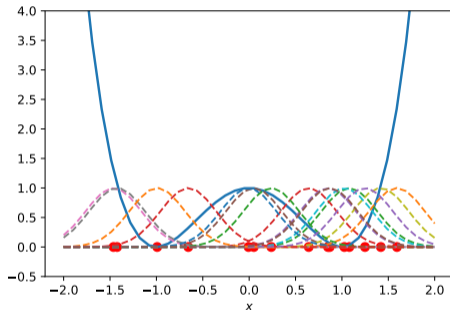


Data-driven Basis Sets

- Choosing a good basis set is hard.



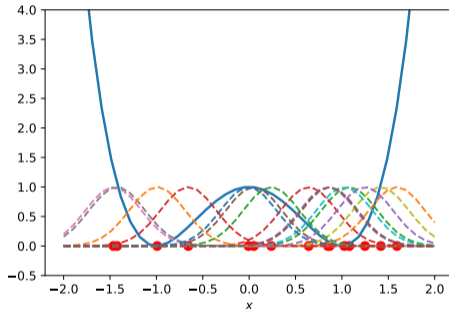
- Choosing a good basis set is hard.
- Idea: let the data define the basis.





Data-driven Basis Sets

- Choosing a good basis set is hard.
- Idea: let the data define the basis.



- Typical choice: **radial basis functions**, e.g.

$$k(x_i, y) = \exp\left(-\frac{1}{2\sigma^2}\|x_i - y\|^2\right)$$



Theorem (Moore-Aronszajn, 1950)

Let \mathbb{X} be a set and $k : \mathbb{X} \times \mathbb{X}$ be a continuous function such that

- (i) $k(x, y) = k(y, x)$ (symmetry)
- (ii) $\sum_{i,j=1}^m \alpha_i \alpha_j k(x_i, x_j) \geq 0$ (positive definiteness).

Then k generates a unique Hilbert space \mathbb{H} of continuous functions such that

- (a) $\mathbb{H} = \overline{\text{span}\{k(x, \cdot), x \in \mathbb{X}\}}$,
- (b) $\langle f, k(x, \cdot) \rangle_{\mathbb{H}} = f(x) \quad \forall f \in \mathbb{H}$ (reproducing property).



Theorem (Moore-Aronszajn, 1950)

Let \mathbb{X} be a set and $k : \mathbb{X} \times \mathbb{X}$ be a continuous function such that

- (i) $k(x, y) = k(y, x)$ (symmetry)
- (ii) $\sum_{i,j=1}^m \alpha_i \alpha_j k(x_i, x_j) \geq 0$ (positive definiteness).

Then k generates a unique Hilbert space \mathbb{H} of continuous functions such that

- (a) $\mathbb{H} = \overline{\text{span}\{k(x, \cdot), x \in \mathbb{X}\}}$,
- (b) $\langle f, k(x, \cdot) \rangle_{\mathbb{H}} = f(x) \quad \forall f \in \mathbb{H}$ (reproducing property).

Facts:

- Gaussian RBF kernel is a valid kernel.



Theorem (Moore-Aronszajn, 1950)

Let \mathbb{X} be a set and $k : \mathbb{X} \times \mathbb{X}$ be a continuous function such that

- (i) $k(x, y) = k(y, x)$ (symmetry)
- (ii) $\sum_{i,j=1}^m \alpha_i \alpha_j k(x_i, x_j) \geq 0$ (positive definiteness).

Then k generates a unique Hilbert space \mathbb{H} of continuous functions such that

- (a) $\mathbb{H} = \overline{\text{span}\{k(x, \cdot), x \in \mathbb{X}\}}$,
- (b) $\langle f, k(x, \cdot) \rangle_{\mathbb{H}} = f(x) \quad \forall f \in \mathbb{H}$ (reproducing property).

Facts:

- Gaussian RBF kernel is a valid kernel.
- Many popular kernels correspond to infinite-dimensional RKHSs.



Theorem (Moore-Aronszajn, 1950)

Let \mathbb{X} be a set and $k : \mathbb{X} \times \mathbb{X}$ be a continuous function such that

- (i) $k(x, y) = k(y, x)$ (symmetry)
- (ii) $\sum_{i,j=1}^m \alpha_i \alpha_j k(x_i, x_j) \geq 0$ (positive definiteness).

Then k generates a unique Hilbert space \mathbb{H} of continuous functions such that

- (a) $\mathbb{H} = \overline{\text{span}\{k(x, \cdot), x \in \mathbb{X}\}}$,
- (b) $\langle f, k(x, \cdot) \rangle_{\mathbb{H}} = f(x) \quad \forall f \in \mathbb{H}$ (reproducing property).

Facts:

- Gaussian RBF kernel is a valid kernel.
- Many popular kernels correspond to infinite-dimensional RKHSs.
- These RKHSs are dense in most L^2 -spaces.



- Applying EDMD to kernel-based basis functions $k(x_i, \cdot)$ leads to matrices...

$$\mathbf{K}_{\mathbb{H}}^t = \mathbf{K}_X^{-1} \mathbf{K}_X^t, \quad \mathbf{K}_X(r, s) = k(x_r, x_s), \quad \mathbf{K}_X^t(r, s) = k(y_r, x_s).$$

- ... or to the generalized eigenvalue problem:

$$\mathbf{K}_X^t \mathbf{w}_i = \lambda_i(t) \mathbf{K}_X \mathbf{w}_i.$$

Klus et al, *J. Nonlinear Sci.*, 2020; Klus, **FN**, and Hamzi, *Entropy*, 2020



- Applying EDMD to kernel-based basis functions $k(x_i, \cdot)$ leads to matrices...

$$\mathbf{K}_{\mathbb{H}}^t = \mathbf{K}_X^{-1} \mathbf{K}_X^t, \quad \mathbf{K}_X(r, s) = k(x_r, x_s), \quad \mathbf{K}_X^t(r, s) = k(y_r, x_s).$$

- ... or to the generalized eigenvalue problem:

$$\mathbf{K}_X^t \mathbf{w}_i = \lambda_i(t) \mathbf{K}_X \mathbf{w}_i.$$

- For infinite data, converges to cross-covariance operators:

$$\mathcal{K}_X f = \int_{\mathbb{X}} f(x) k(x, \cdot) d\mu(x), \quad \mathcal{K}_X^t f = \int_{\mathbb{X}} \mathcal{K}^t f(x) k(x, \cdot) d\mu(x).$$

Klus et al, *J. Nonlinear Sci.*, 2020; Klus, **FN**, and Hamzi, *Entropy*, 2020



1. The Koopman Operator and EDMD
2. Variational Approach (VAC)
3. EDMD and Kernels
4. Random Fourier Features for EDMD



- Recall kernelized eigenvalue problem:

$$\mathbf{K}_X^t \mathbf{w}_i = \lambda_i(t) \mathbf{K}_X \mathbf{w}_i, \quad \mathbf{K}_X(r, s) = k(x_r, x_s), \quad \mathbf{K}_X^t(r, s) = k(y_r, x_s).$$

- Kernel matrices are often low-rank; require **low-rank decomposition** of \mathbf{K}_X .
- Straightforward approach scales as $\mathcal{O}(m^3)$.
- Needs to be solved **many times** to accurately tune kernel parameters.
- Requires efficient low-rank approximation, e.g. Nyström methods, random linear algebra, random Fourier features,...



- A translation invariant kernel with $k(x, x) = 1$ can be written as

$$K(x, y) = \mathbb{E}^{\omega \sim \rho} \left[e^{-i\omega^T x} \overline{e^{-i\omega^T y}} \right] \approx \frac{1}{p} \sum_{u=1}^p e^{-i\omega_u^T x} \overline{e^{-i\omega_u^T y}}.$$

where ρ is the **spectral measure** in frequency space (Bochner's theorem).

- The spectral measure is known for most popular kernels, sampling from ρ is easy.

Rahimi and Recht, Advances in Neural Information Processing Systems, 2007

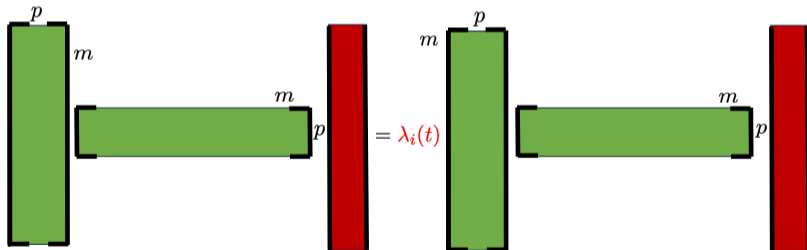


- Low-rank rep of kernel Koopman GEV:

$$\mathbf{K}_X = [k(x_r, x_s)]_{r,s} \approx \frac{1}{p} [\mathbf{M}\mathbf{M}^H]_{r,s}, \quad \mathbf{K}_X^t = [k(y_r, x_s)]_{r,s} \approx \frac{1}{p} [\mathbf{M}^t\mathbf{M}^H]_{r,s},$$

$$\mathbf{M} = \left[e^{-ix_r^\top \omega_u} \right]_{r,u} \in \mathbb{R}^{m \times p},$$

$$\mathbf{M}^t = \left[e^{-iy_r^\top \omega_u} \right]_{r,u} \in \mathbb{R}^{m \times p}.$$

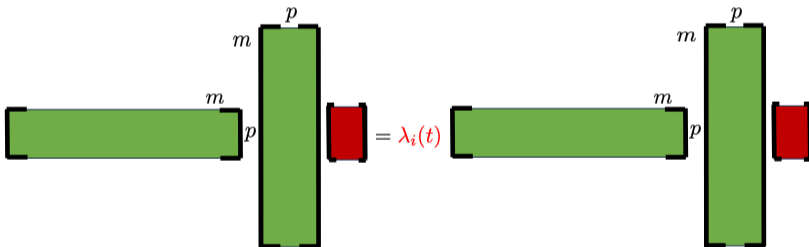




- Non-zero eigenvalues can be obtained from dual problem

$$\mathbf{M}^H \mathbf{M}^t \mathbf{v}_i = \hat{\lambda}_i(t) \mathbf{M}^H \mathbf{M} \mathbf{v}_i,$$

which is of dimension $p \times p$.



FN and Klus, J. Chem. Phys., 2023



- The dual eigenvalue problem

$$\mathbf{M}^H \mathbf{M}^t \mathbf{v}_i = \hat{\lambda}_i(t) \mathbf{M}^H \mathbf{M} \mathbf{v}_i,$$

can be solved by operating only on \mathbf{M} , \mathbf{M}^t .

- If p is significantly smaller than m , cost is $\mathcal{O}(mp^2)$ instead of $\mathcal{O}(m^3)$.
- Dual GEV is the EDMD eigenvalue problem for a **randomized, complex-valued basis set** of plane waves:

$$\phi_{\text{RFF}}(x) := \begin{bmatrix} \phi_1(x) \\ \vdots \\ \phi_p(x) \end{bmatrix} = \begin{bmatrix} e^{ix^\top \omega_1} \\ \vdots \\ e^{ix^\top \omega_p} \end{bmatrix}.$$

FN and Klus, J. Chem. Phys., 2023



Small protein with 39 amino acids, use Gaussian kernel on 666 inter-residue distances, $m = 15.000$ data points in real space.

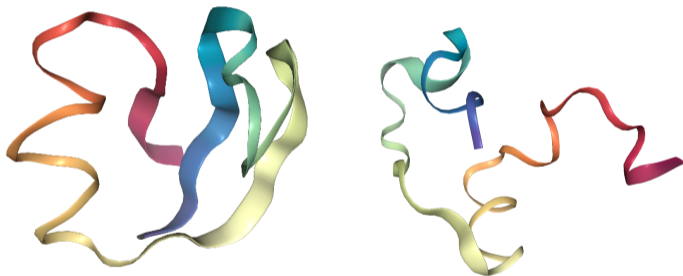
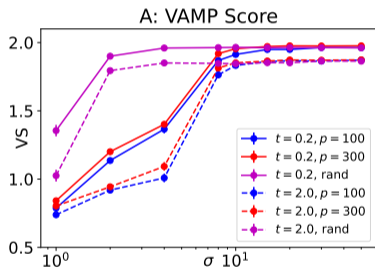


Figure: VAMP Score and Representatives of PCCA States for NTL9



Conclusions

1. Koopman framework provides a linear view of dynamical systems, Galerkin projections can be learned consistently from simulation data.
2. Variational Score (VAMP) is a principled way of choosing model classes, especially for metastable systems.
3. Kernel Methods provide a powerful data-driven basis set with well-understood asymptotic properties.
4. Random Fourier features appear as a promising candidate for efficient low-rank approx. of resulting linear algebra problems.

Main Collaborators: Stefan Klus (Heriot-Watt U, Edinburgh), Sebastian Peitz (U Paderborn), Frank Noé (Freie U Berlin), Cecilia Clementi (Freie U Berlin)

References:

- **FN**, Keller, Pérez-Hernández, Mey, Noé, *Variational Approach to Molecular Kinetics*, JCTC 10 (4), 1739-1752, 2014
- Klus, **FN**, Koltai, Wu, Kevrekidis, Schütte, Noé, *Data-driven model reduction and transfer operator approximation*, Journal of Nonlinear Science, 28, 985-1010, 2018
- Klus, **FN**, Peitz, et al, *Data-driven approximation of the Koopman generator: Model reduction, system identification, and control*, Physica D, 406, 132416, 2020
- Klus, **FN**, Hamzi, *Kernel-Based Approximation of the Koopman Generator and Schrödinger Operator*, Entropy 22 (7), 722, 2020
- **FN** and Klus, *Efficient Approximation of Molecular Kinetics using Random Fourier Features*, Journal of Chemical Physics 159, 074105, 2023